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A Mathematical Introduction to Robotic Manipulation presents a mathematical formulation of the kinematics, dynamics, and control of robot manipulators. It uses an elegant set of mathematical tools that emphasizes the geometry of robot motion and allows a large class of robotic manipulation problems to be analyzed within a unified framework.

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a slightly more abstract (mathematical) formulation of the kinematics, dynamics, and control of robot manipulators. The current book is an attempt to provide this formulation not just for a single robot but also for multifingered robot hands, involving multiple cooperating robots. It

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But this book on robotics is a worthy rejoinder. It can be regarded as an advanced text in classical mechanics. It shows how mathematical treatments of rigid and non-rigid body rotations and displacements are necessary to correctly model robot manipulators. Plus how holonomic constraints can be used to determine system behaviour.

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